

## Winner

## **Best Student Paper Award**

The 3rd International Symposium on Swarm Behavior and Bioinspired Robotics

Formation Control for Multiple Quadrotors Based on Optimal Regulation of Individual and Cooperative Performance Outputs

Yusuke Kamitani and Daisuke Tsubakino

The 3rd International Symposium on Swarm Behavior and Bioinspired Robotics Okinawa, Japan, November 22, 2019

Florentin Wörgötter

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